

# Introduction to Light-Field Imaging II

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# Introduction to Light-Field Imaging

## Part 1

1. Introduction
  - a) Basic Idea
  - b) Available Devices: Raytrix, Lytro, Pelican Imaging, Fraunhofer IOF
2. What is a Light-Field?
  - a) Basic optics: Pinhole model
  - b) Light Field 1.0 vs. 2.0
  - c) Camera Model
3. Towards a real Light Field Camera
  - a) Lens optics
  - b) Depth of Field
  - c) Camera Model
4. Algorithms
  1. Image Synthesis
  2. Depth Estimation
  3. Camera Calibration

## Part 2

1. Multiple-Focus Light Field Camera
  - a) Motivation
  - b) Depth of Field
  - c) Total Covering
2. Applications
  - a) Processing
  - b) 3D Quality Inspection
  - c) 3D Microscopy
  - d) 3D Volumetric Velocimetry
  - e) and more...

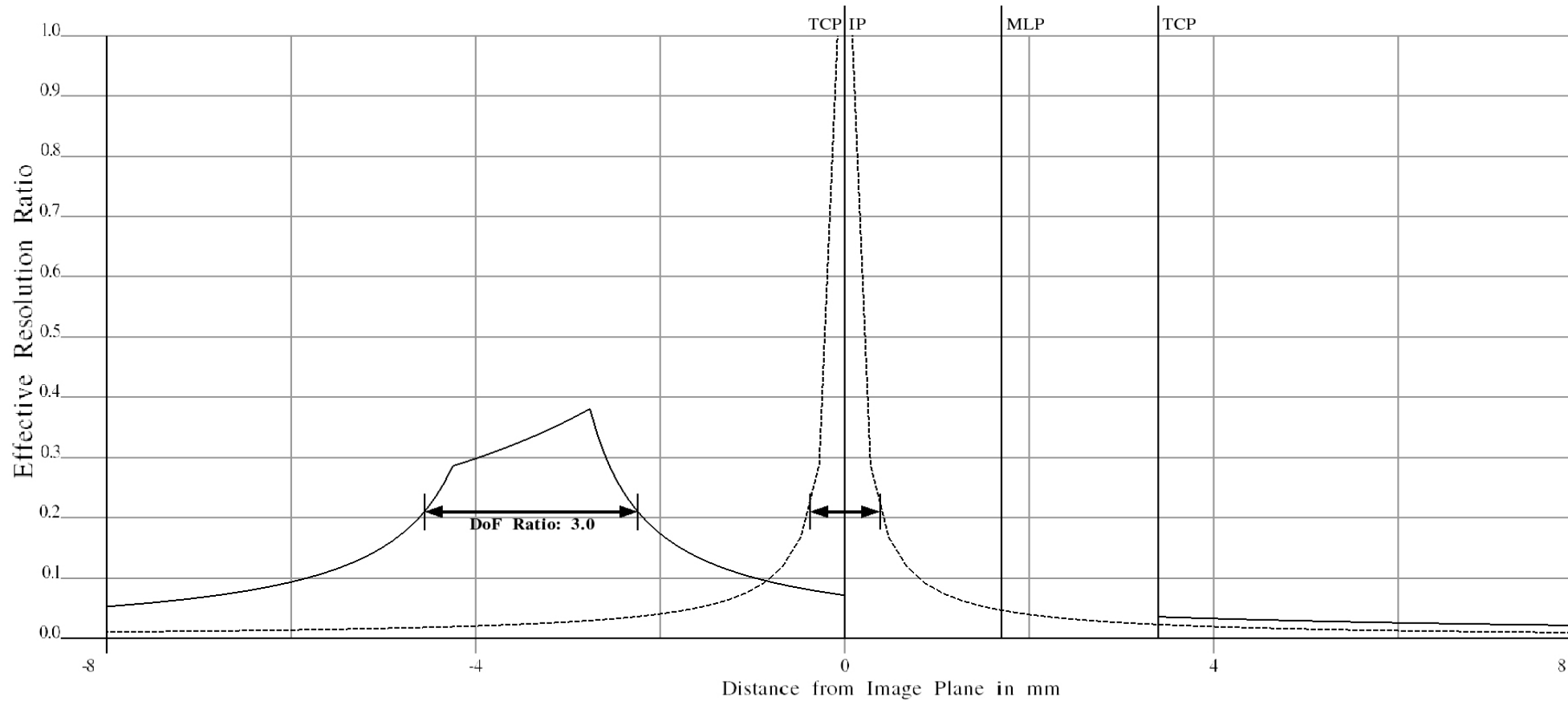


# Multiple Focus Light Field Camera

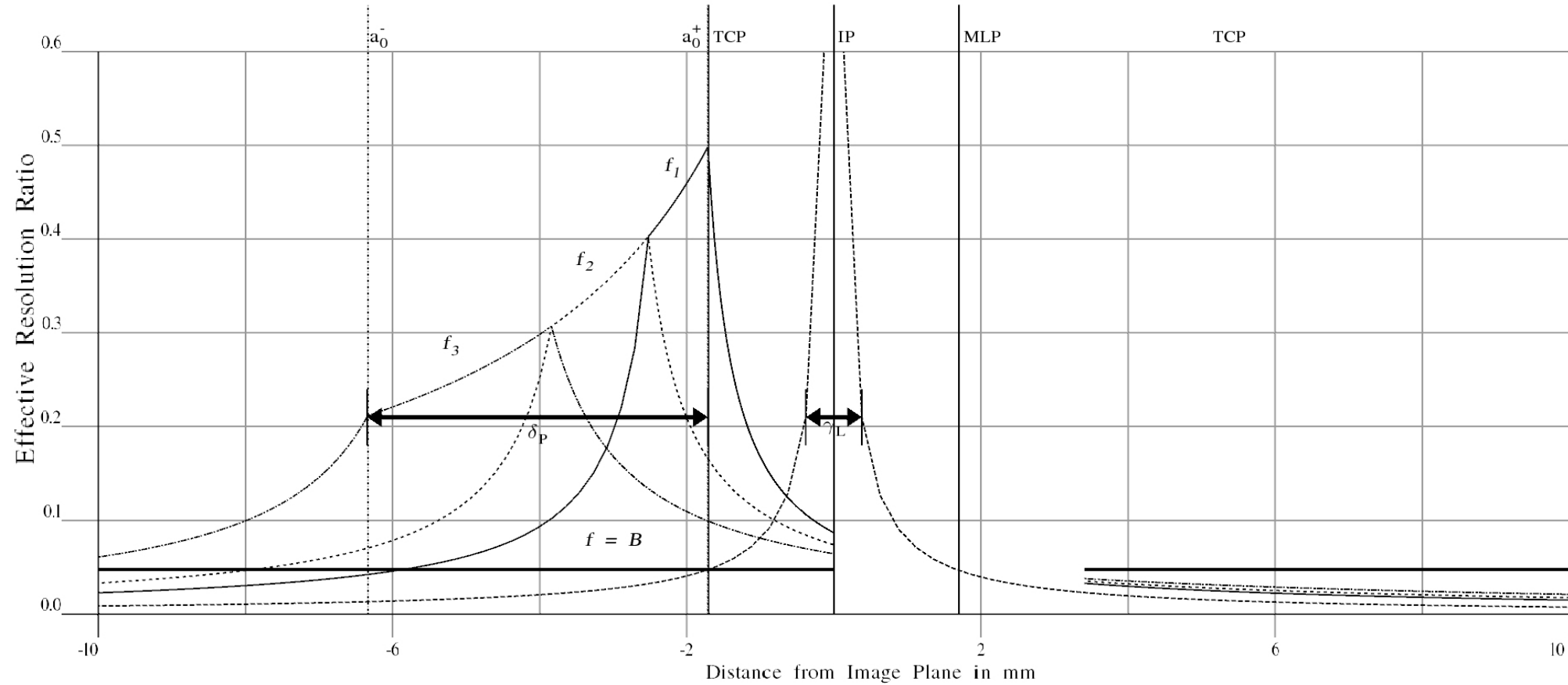


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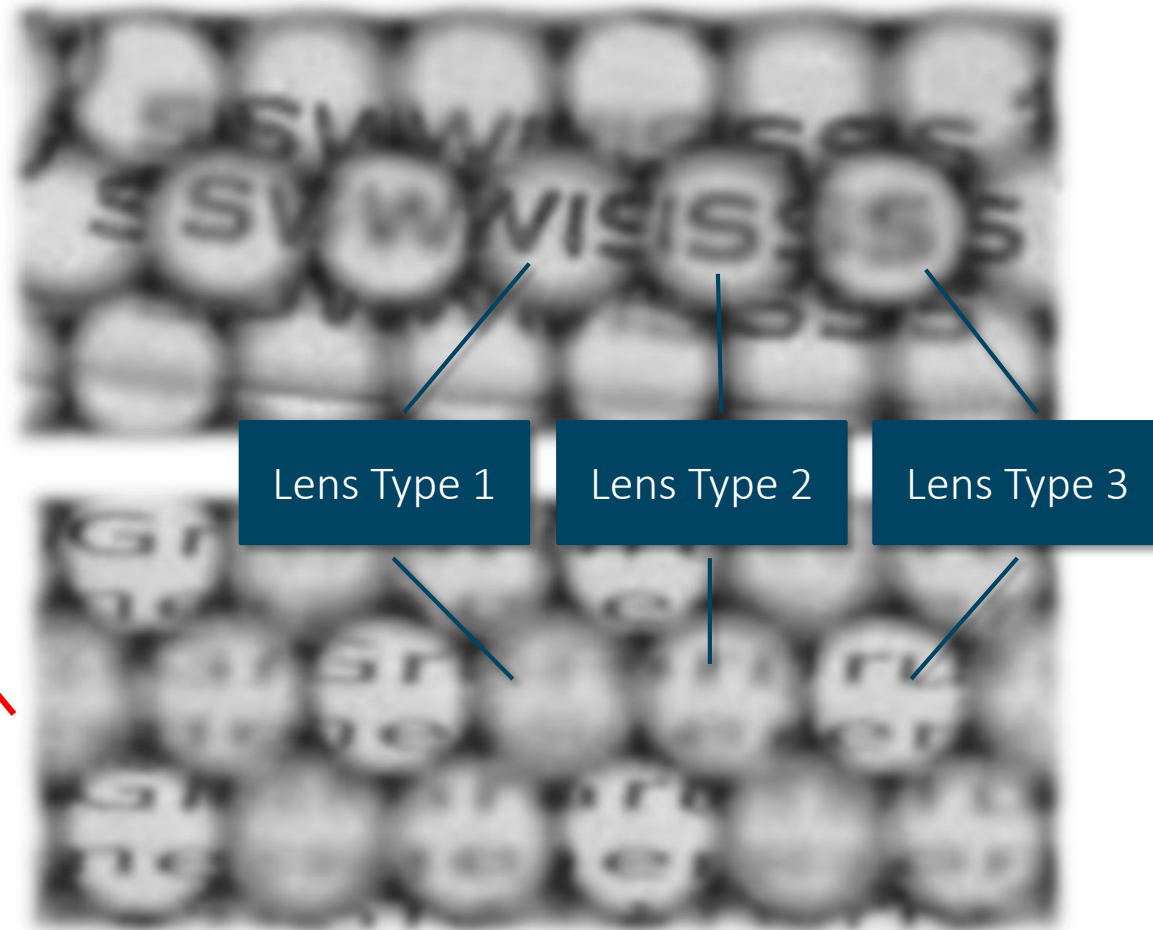
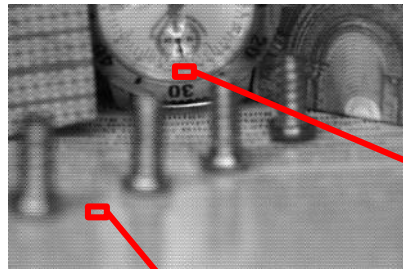
# Recap: Light Field DoF



# Multiple Focus DoF



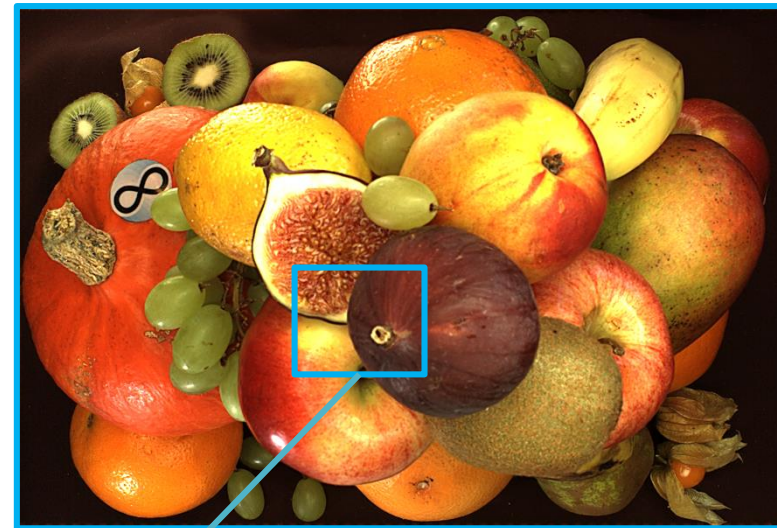
# Multiple Focus Raw Image



# Extended DoF



Standard Camera

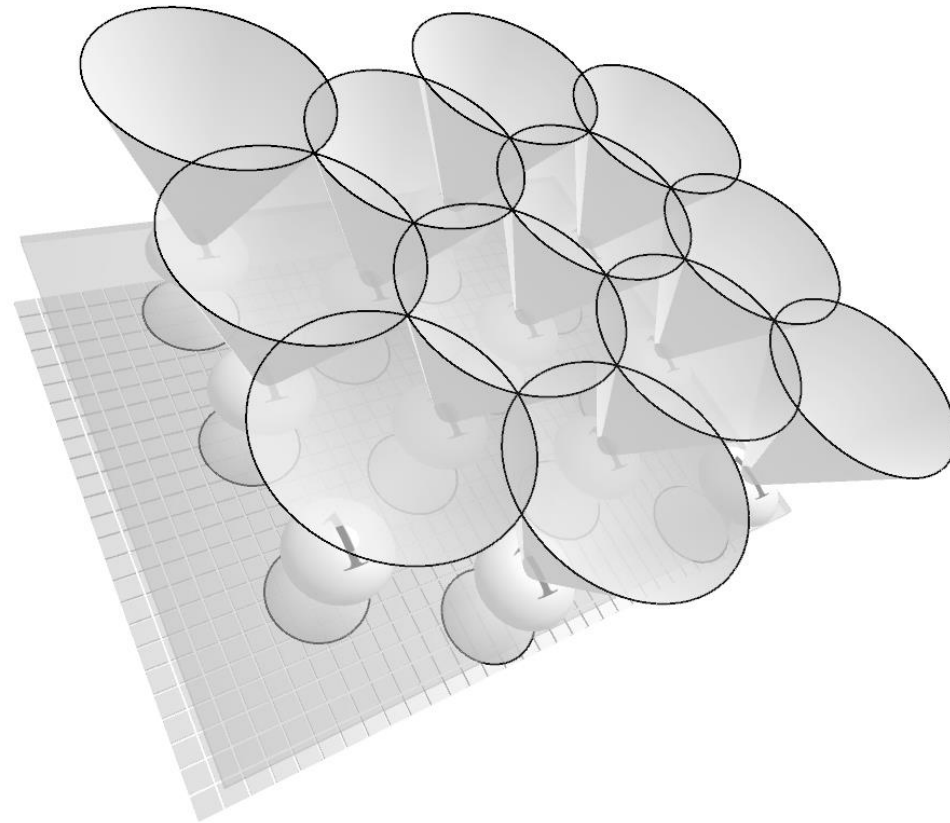


Raytrix Lightfield Camera



Both images were taken with same 11 megapixel sensor, same lens and same aperture.

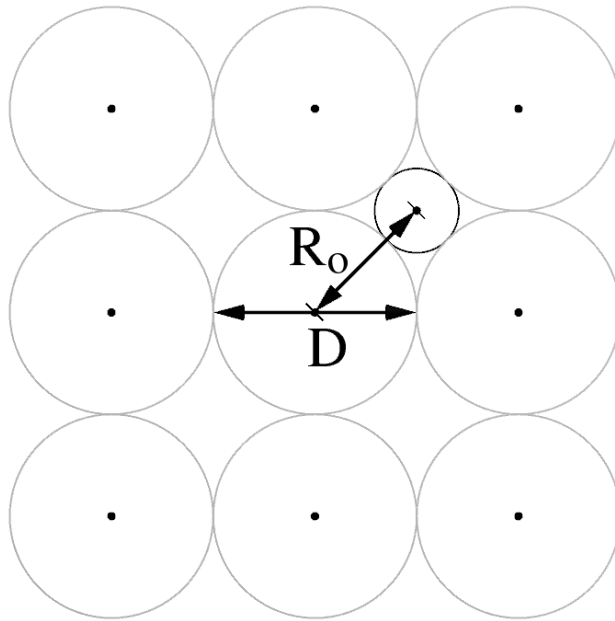
# Total Covering



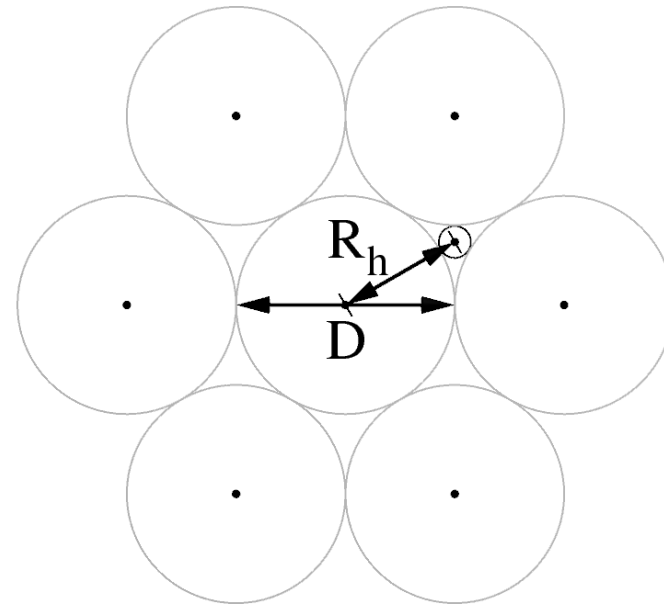
Full MLA Cones Back Cones Front Projection



# Orthogonal vs. Hexagonal Setup



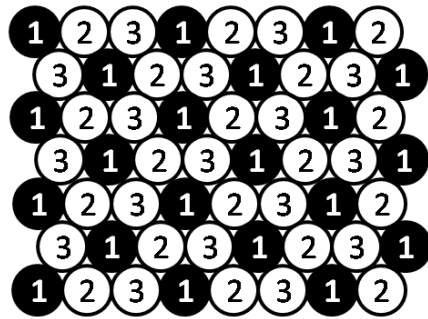
$$R_o = \frac{1}{\sqrt{2}} D \approx 0.71 D$$



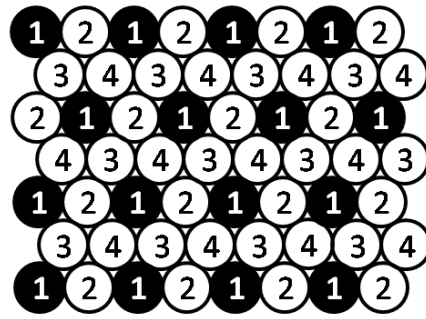
$$R_h = \frac{D}{2} \sqrt{1 + (\tan \pi/6)^2} \approx 0.58 D$$

Total covering is achieved at a smaller distance from the MLA with a hexagonal micro lens setup.

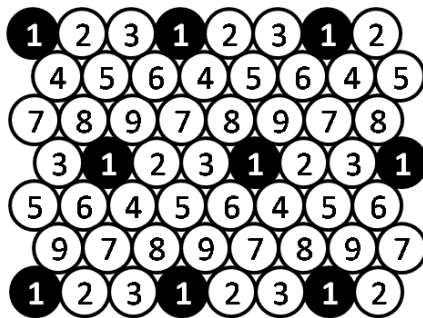
# Lens Type Counts



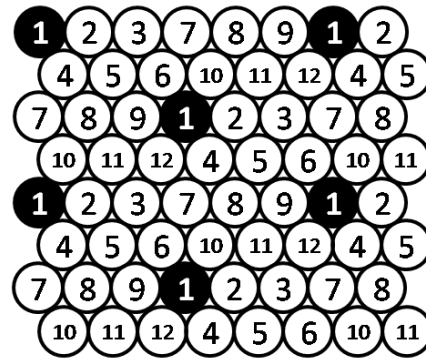
3 Lens Types



4 Lens Types



9 Lens Types



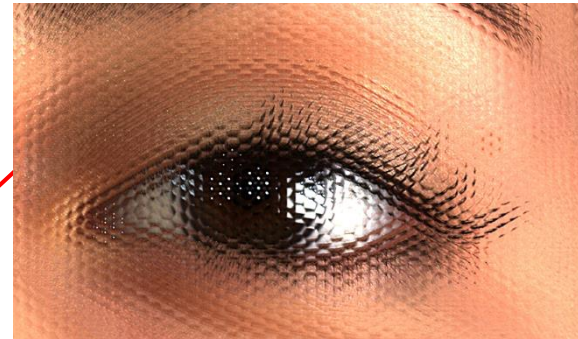
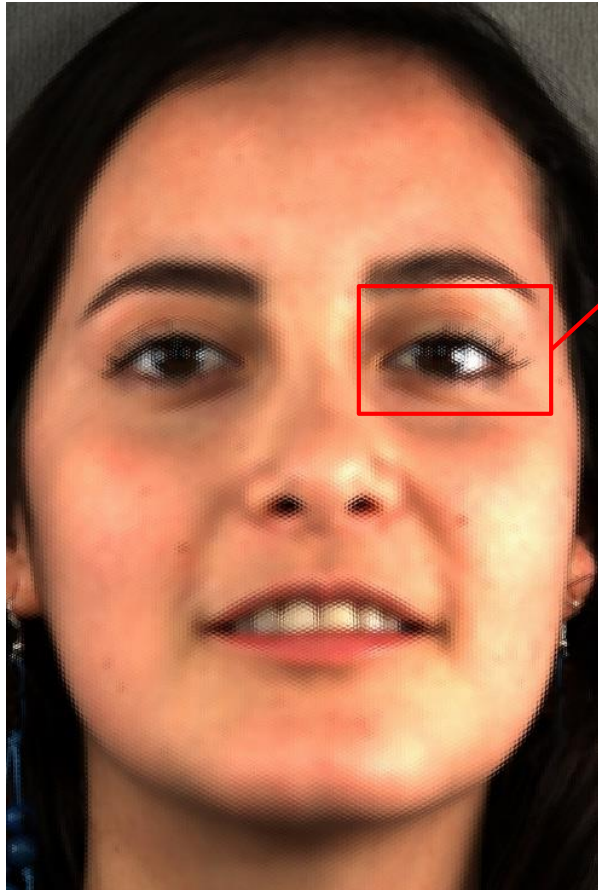
12 Lens Types

To achieve a uniform distribution of lenses of same type, only certain numbers of different lens types are possible.

- 3 Lens Types TCP at  $v = 2.0$
- 4 Lens Types TCP at  $v = 2.15$
- 9 Lens Types TCP at  $v = 2.73$
- 12 Lens Types TCP at  $v = 3.0$

# Application

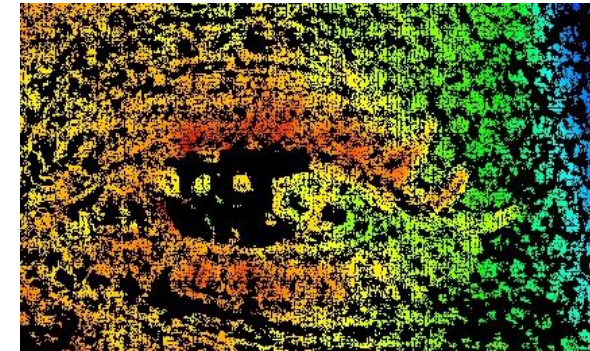
# Image Generation



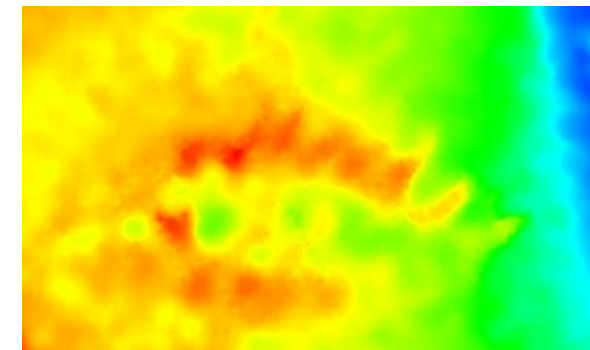
Micro-images show multiple imaging of object parts



Computationally reconstructed image from raw image and depth map

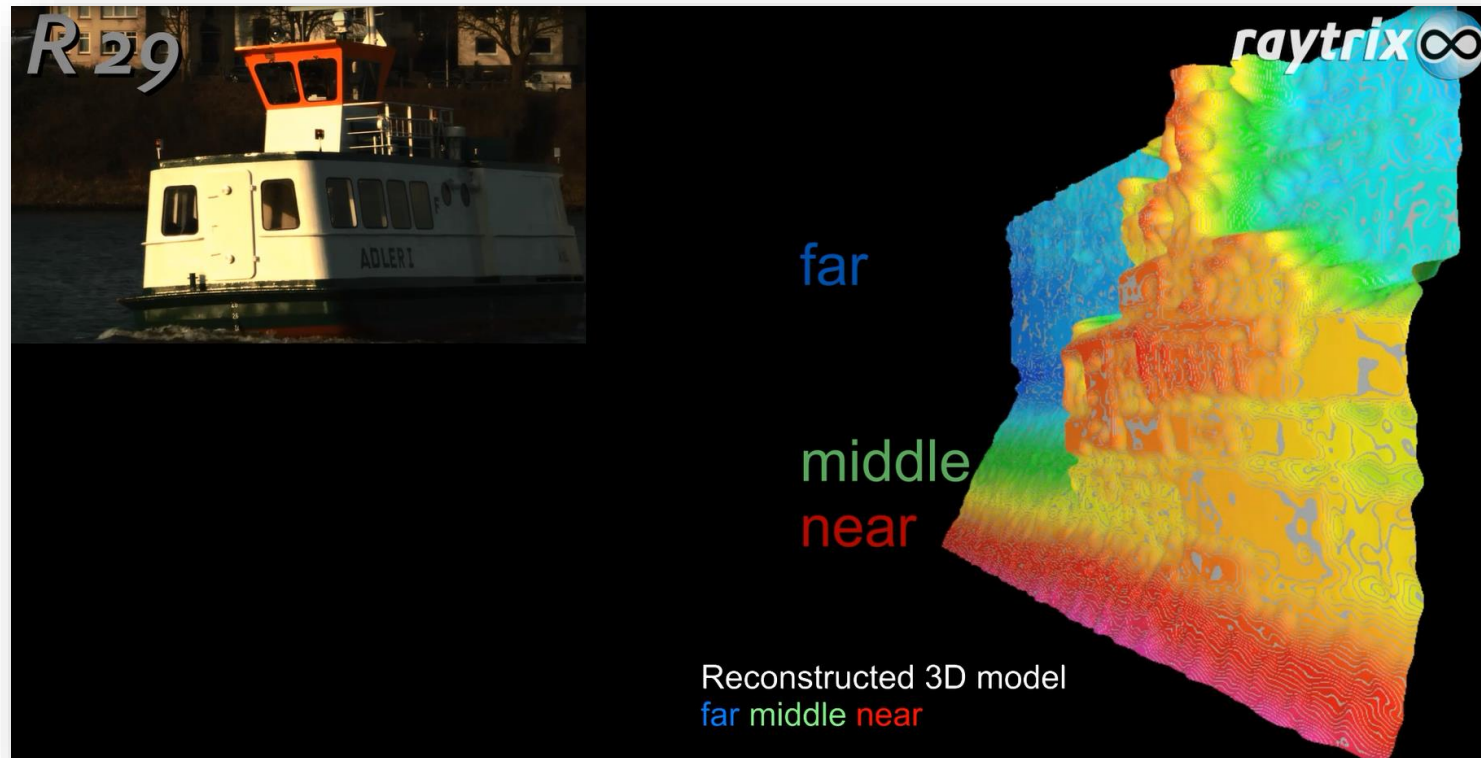


Color-coded depth map for high-contrast areas



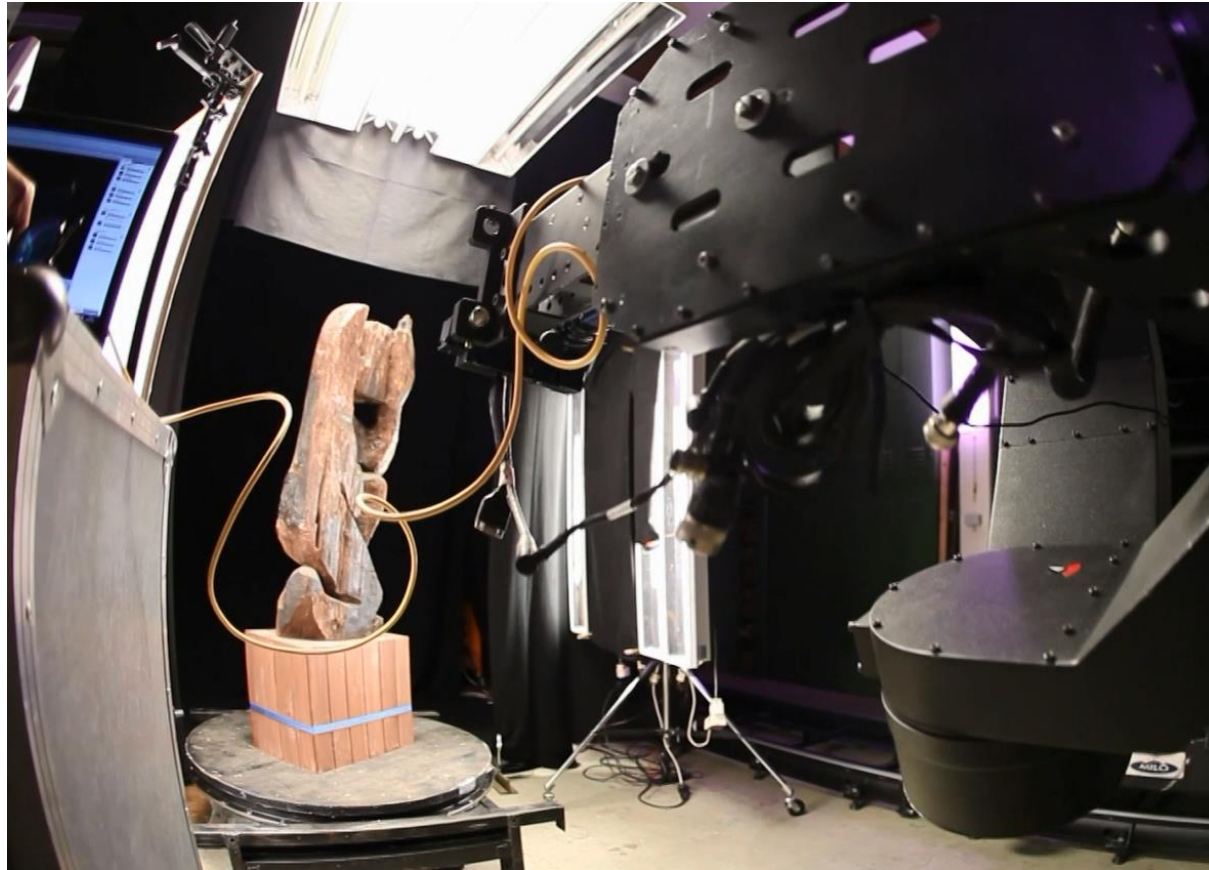
Filled depth map

# Capability Overview



[Show Video](#)

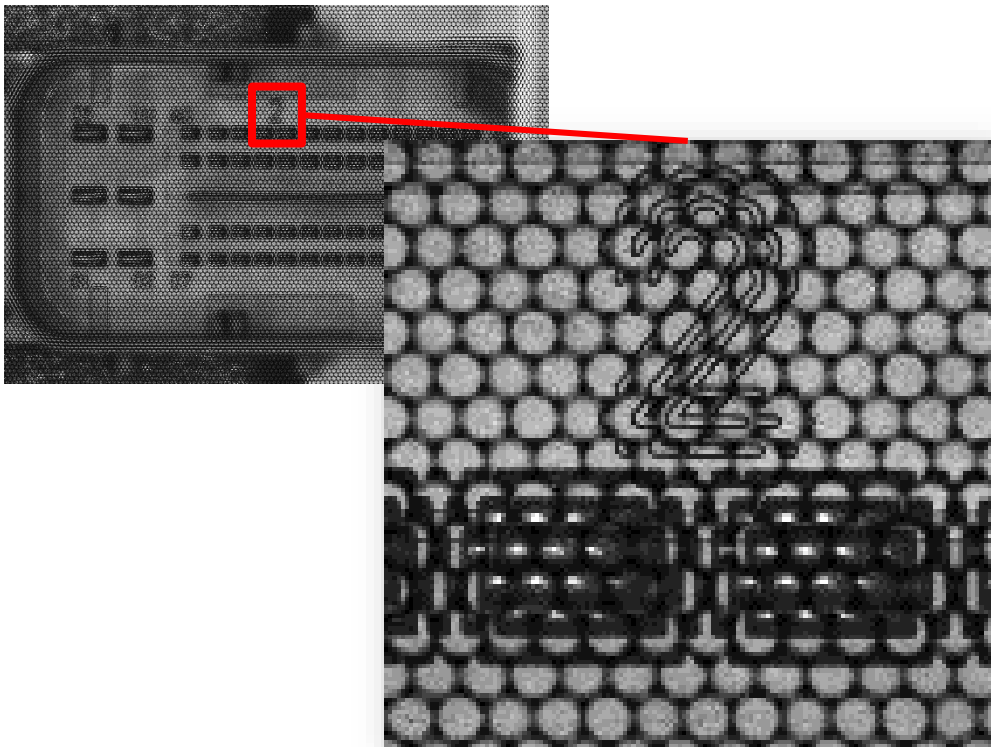
# 3D Capture



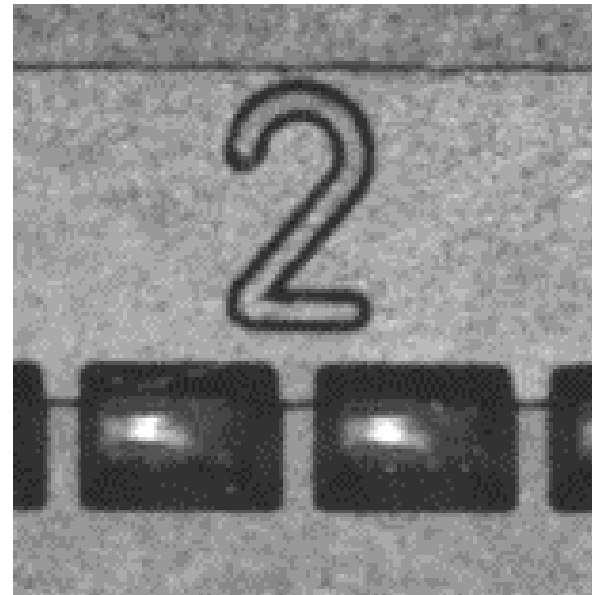
[Show Video](#)

# Quality Inspection

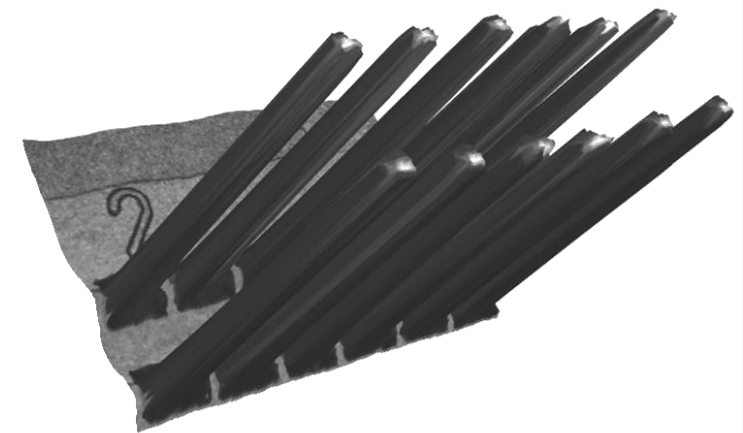
# Pin Inspection



Raw light field image is an array of many micro images



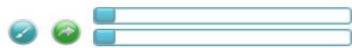
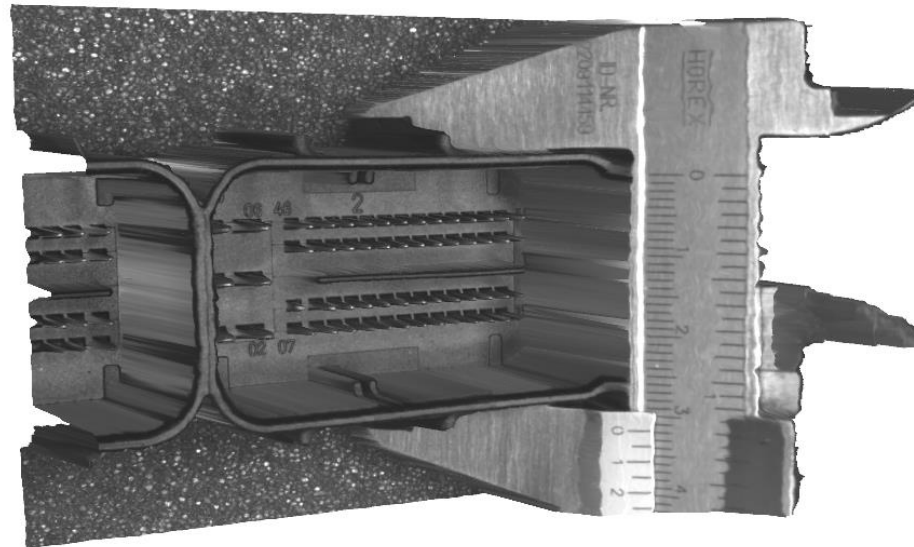
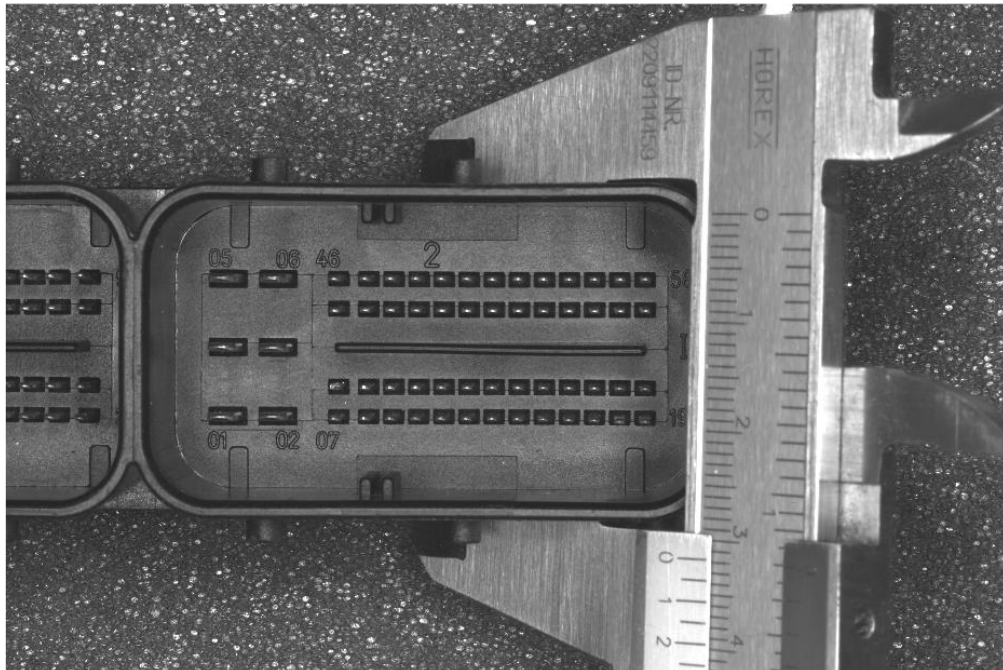
2D Reconstruction



3D Reconstruction

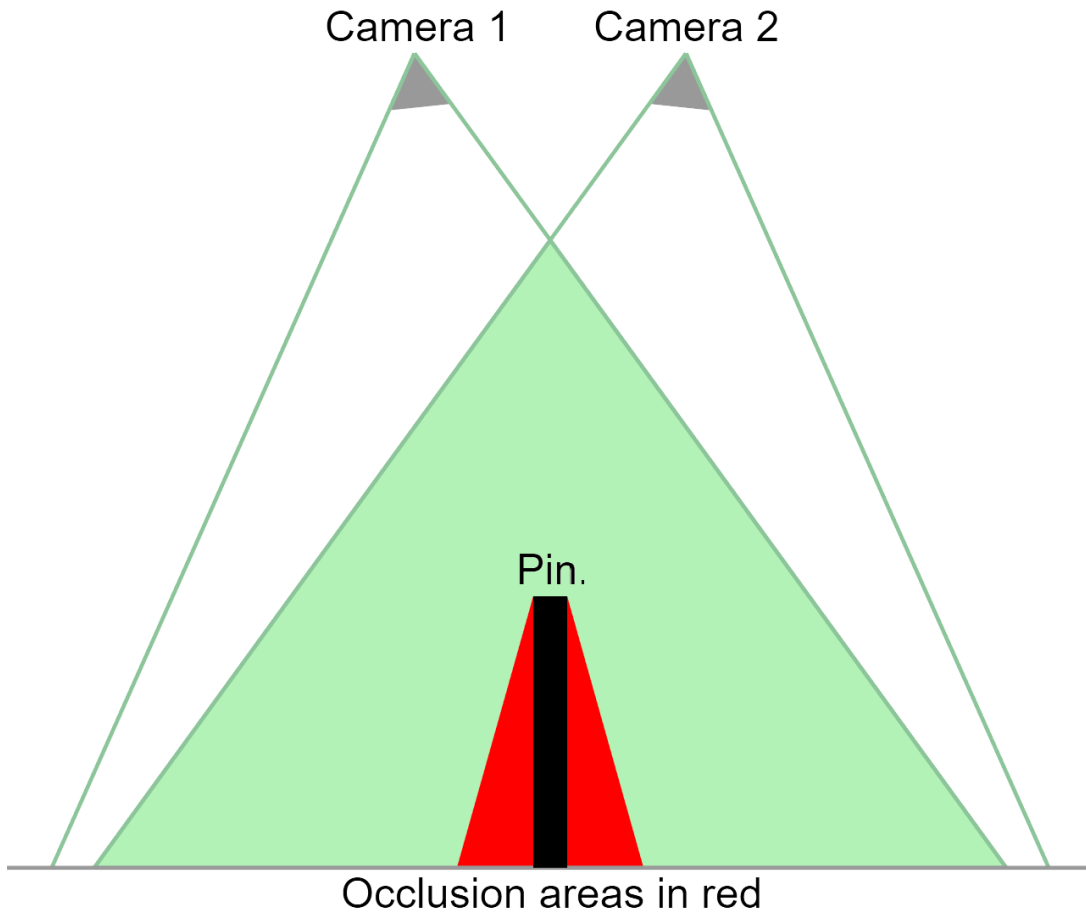


# Pin Inspection

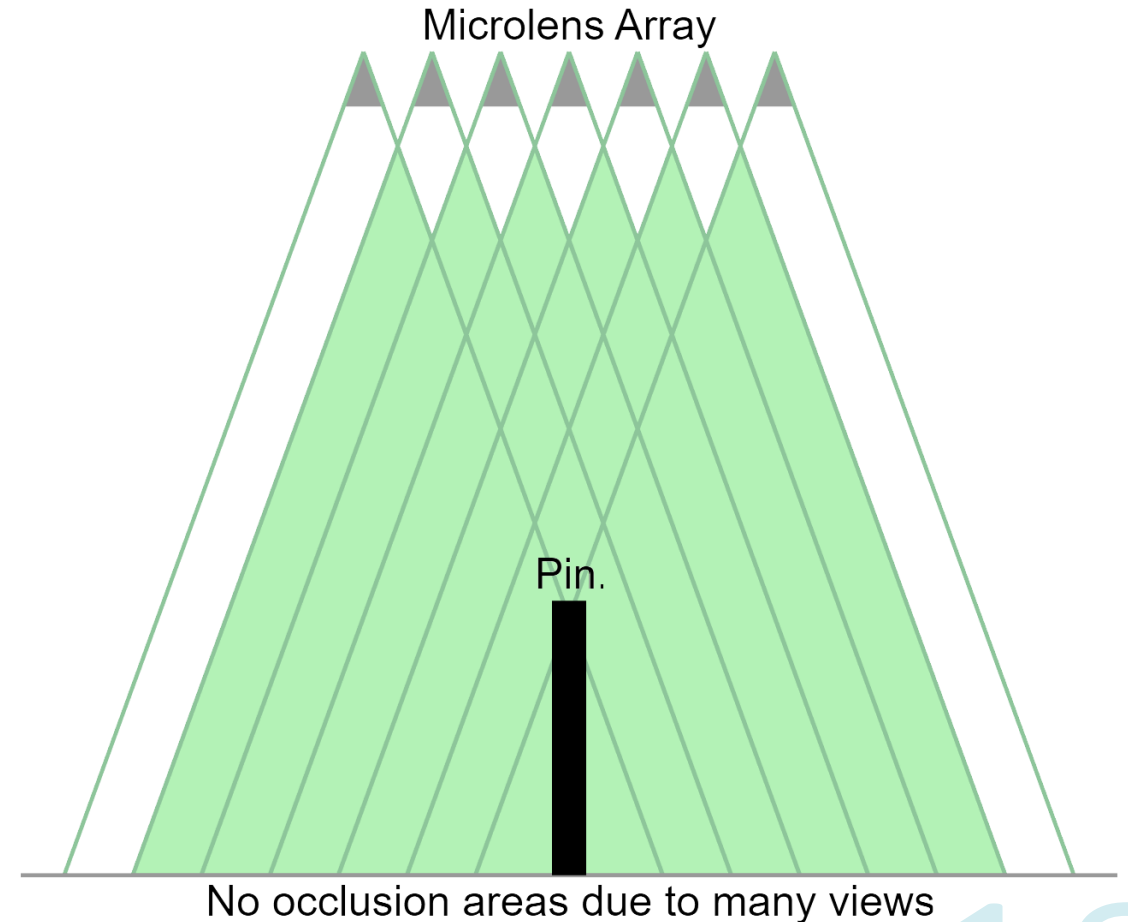


# Occlusion

Stereo Camera System reconstructs pin as cone



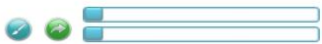
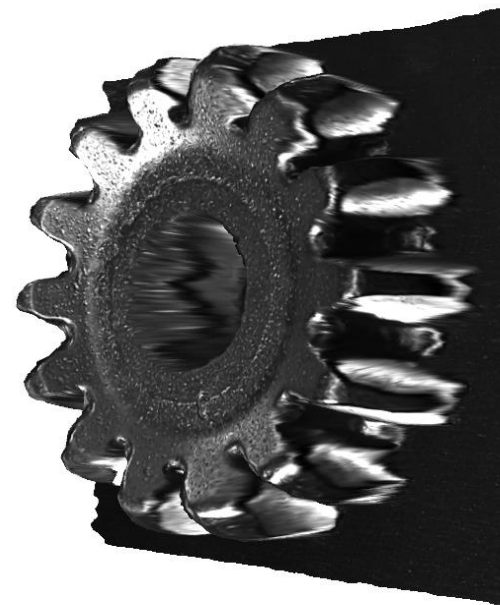
Light Field Camera reconstructs pin as rectangle



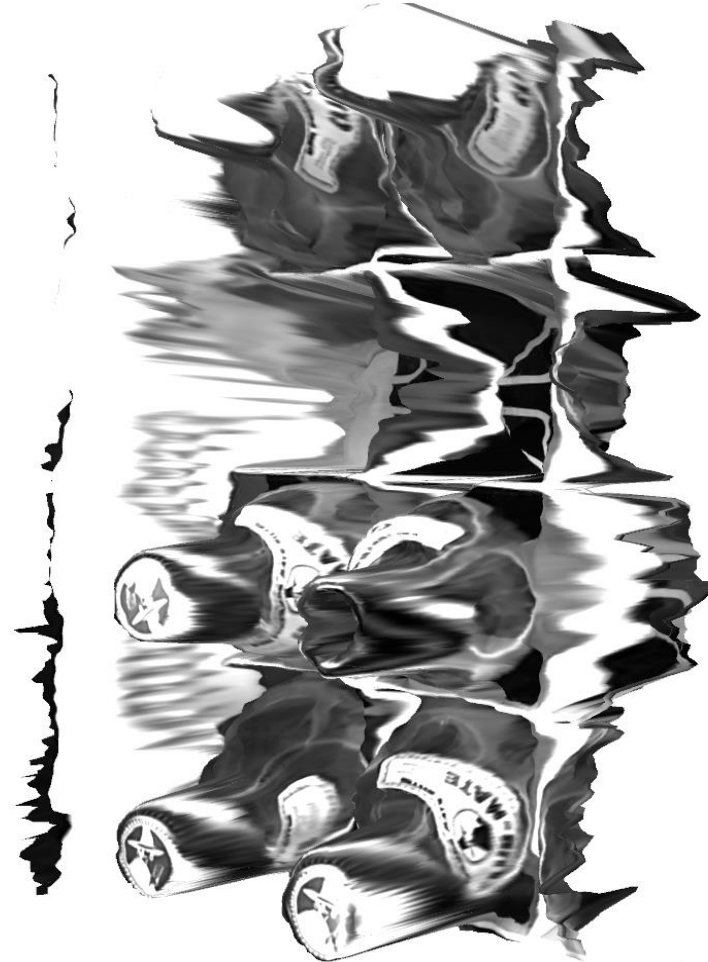
# Pin Inspection



# Inspection



# Bottles





# Light Field Microscopy

# Remarks

- Microscopical optical systems typically have a very high  $f/\#$  on the image side, e.g.  $f/16$ .
- Optical resolution only depends on object side NA.
- Microscopes are basically wide angle optics very close to the object.
- Effect of extended depth of field is particularly pronounced for microscopes.

# Basic LF-Microscope Setup



Microscope Setup

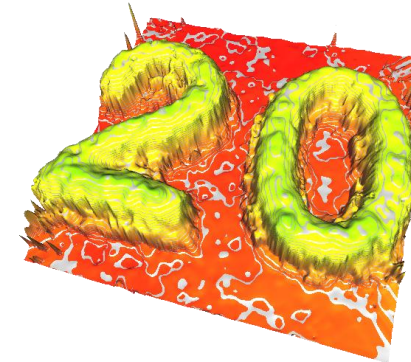
Camera used is R5 with 4MP CMOSIS sensor.



FoV ~ 1x1mm



Total Focus



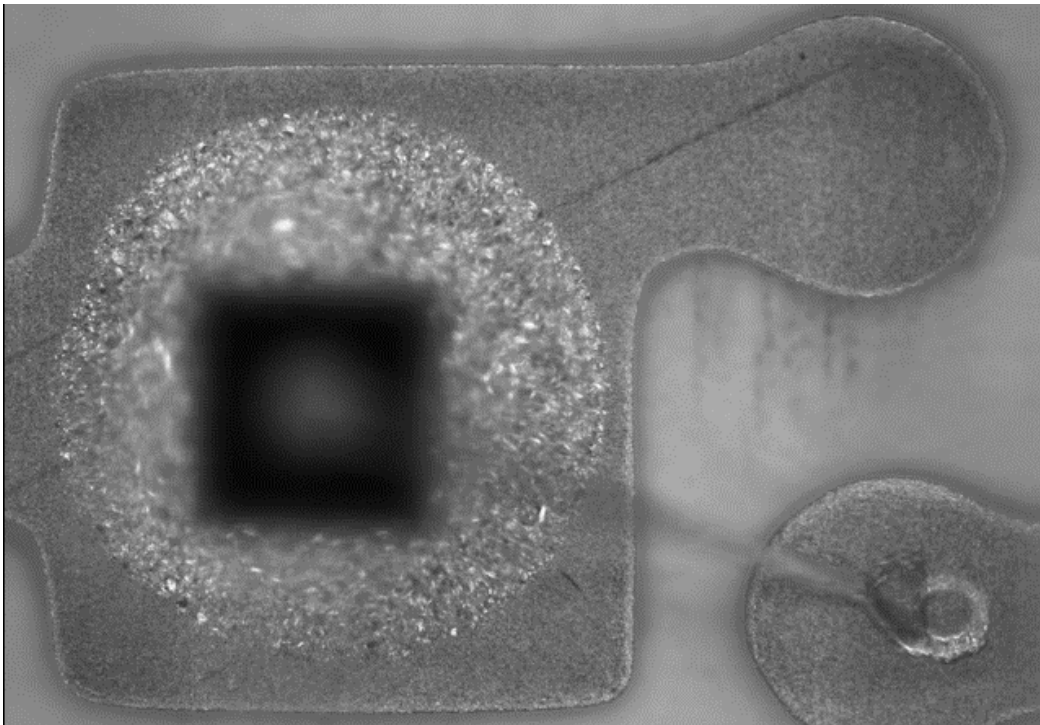
3D Reconstruction



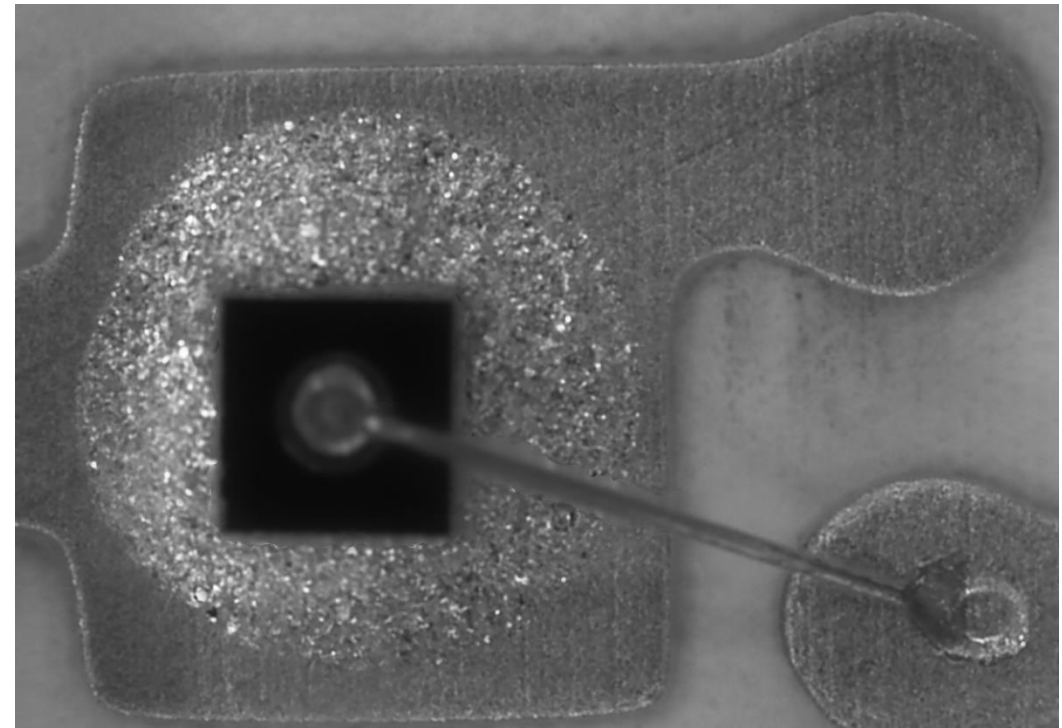
# LF-Microscope DoF

10x Microscope

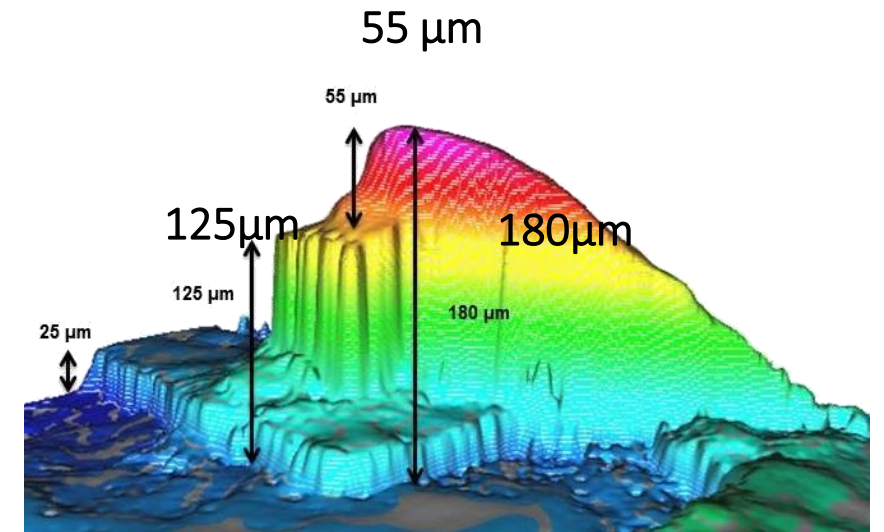
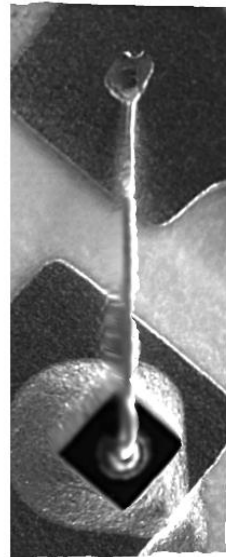
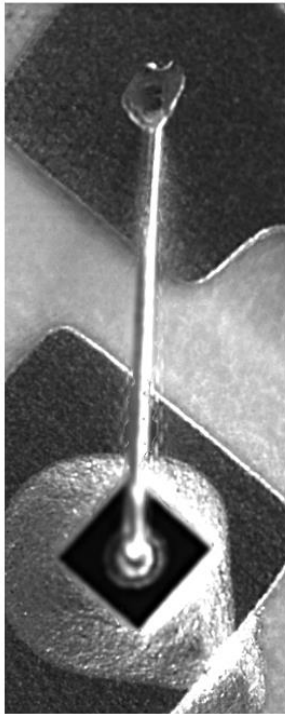
*8 Exposures* at 20 $\mu$ m depth steps with 2D Camera



*Single exposure* with Light Field Camera

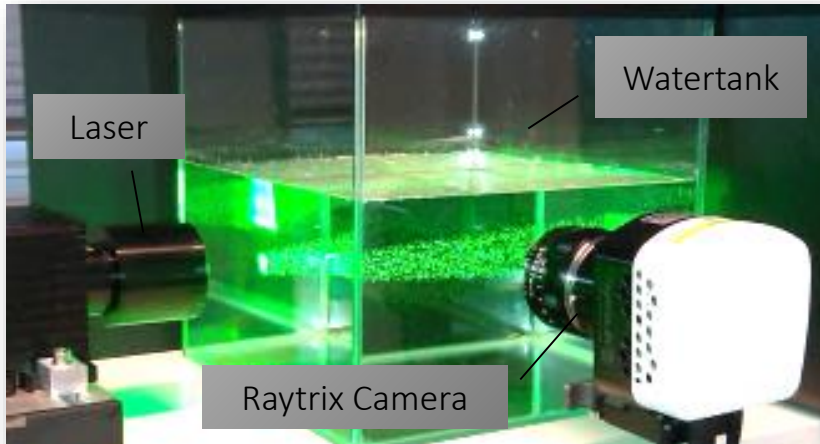


# Bonding Wire

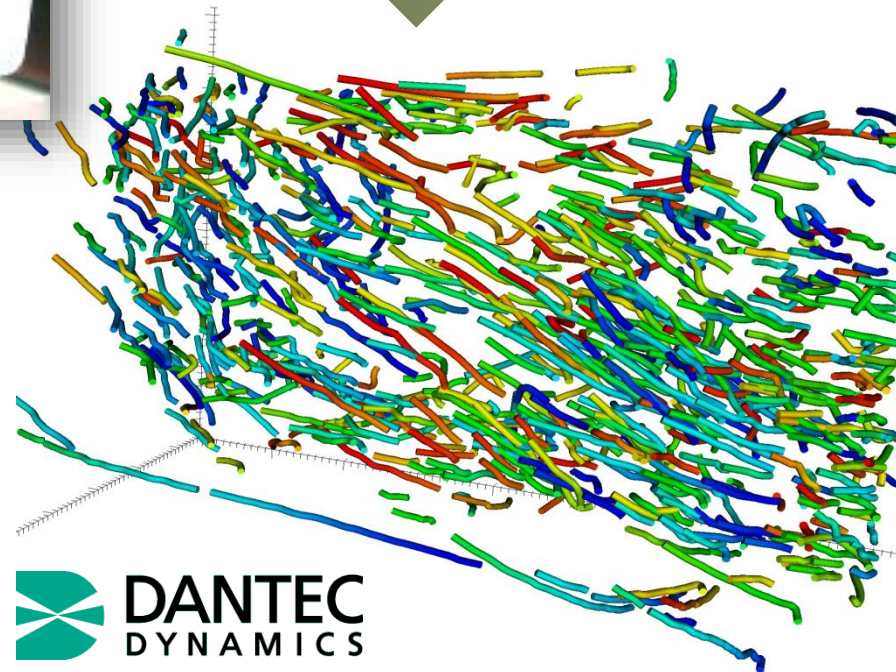


# Light Field Volumetric Velocimetry

# LF-Volumetric Velocimetry Setup

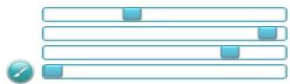
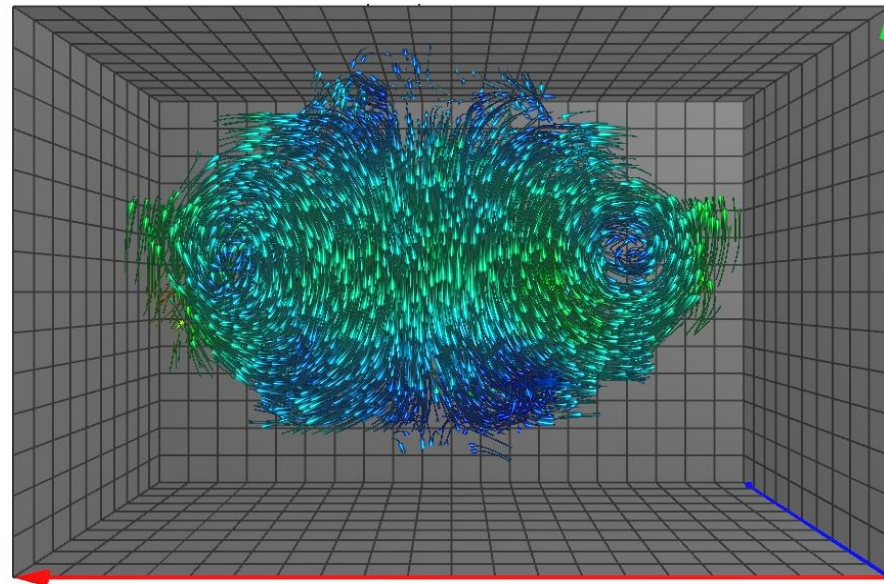


Calculate 3D flow vectors and particle time-histories from lightfield data



- Measure 3D flow of particles in water.
- Need only **one** lightfield camera.
- Simple calibration with single image.
- No need to synchronize cameras.
- Robust setup.

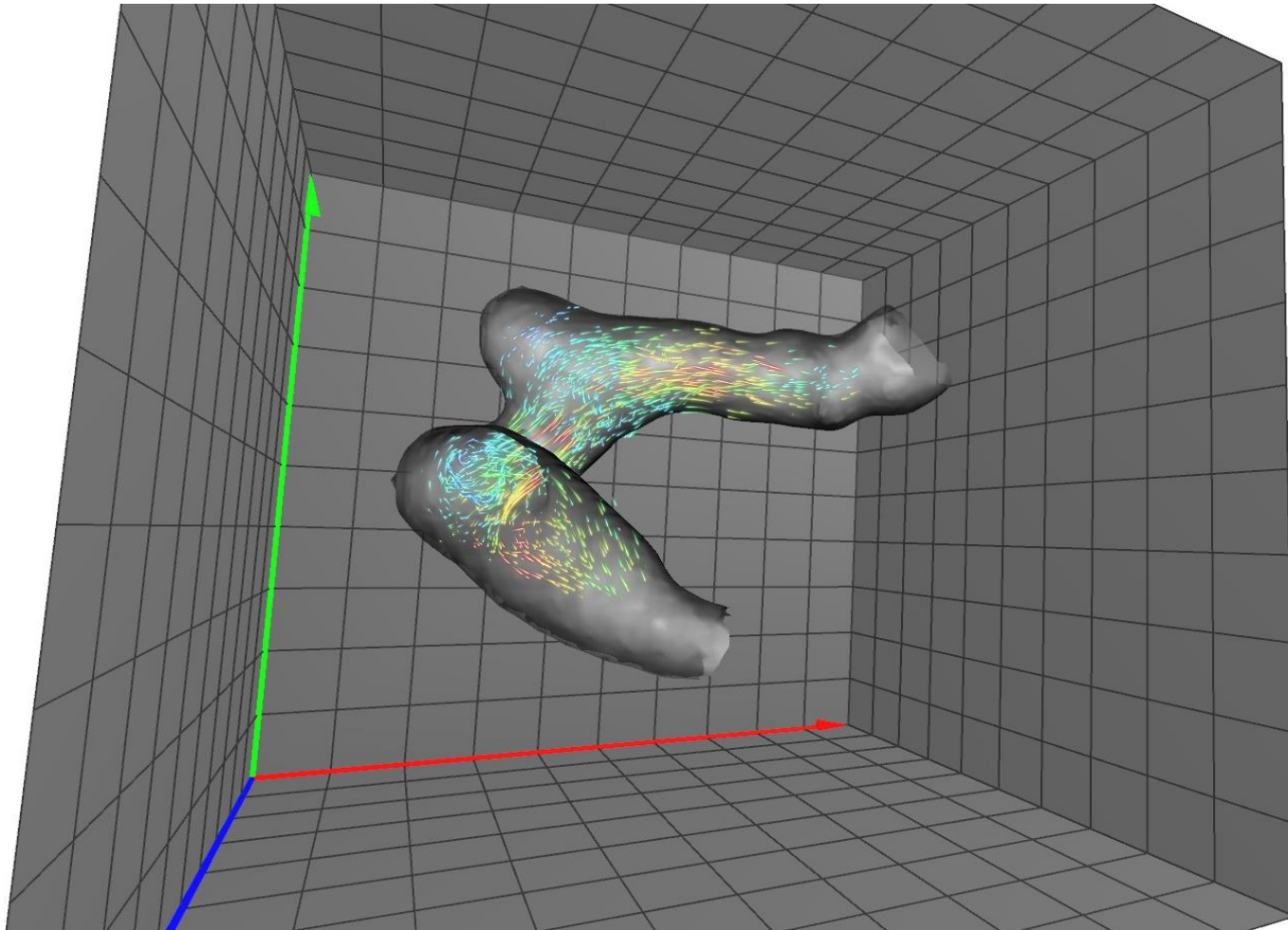
# Toroidal Flow



# Measuring Flow through Aneurysm Model



# Aneurysm Flow



# Miscellaneous



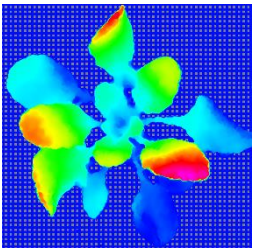
# Faces



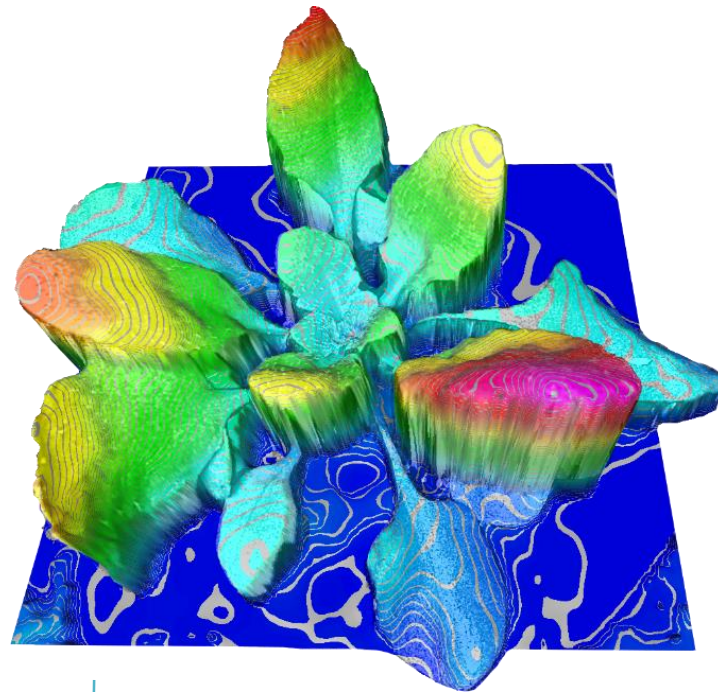
# Phenotyping



2D Image



Depth Map

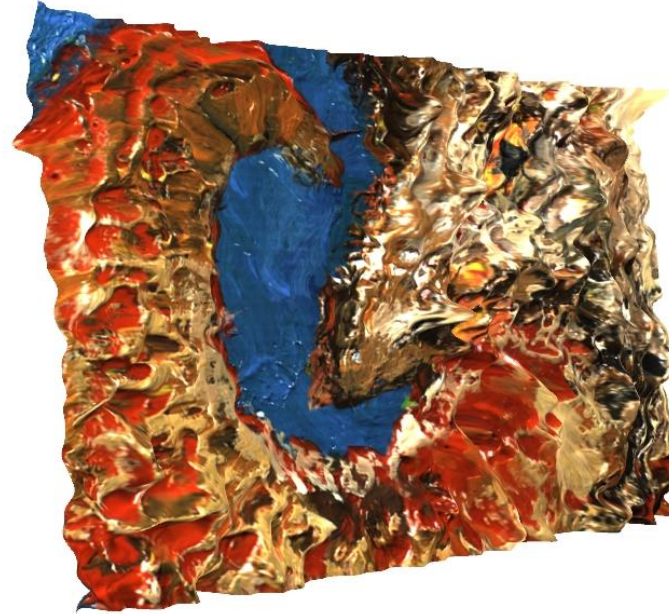


3D View



Raytrix camera with main lens attached and standard lighting. Only a single picture has to be taken to obtain 2D and 3D data.

# Oil Painting





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Thank you for  
your attention!